

White Box Testing Techniques



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Organization of this Lecture



⌘ White-box testing:

- ☑ statement coverage
- ☑ path coverage
- ☑ branch testing
- ☑ condition coverage
- ☑ Cyclomatic complexity

⌘ Summary

White-box Testing

⌘ Designing white-box test cases:

☑ requires knowledge about the internal structure of software.

☑ white-box testing is also called structural testing.

White-Box Testing

⌘ There exist several popular white-box testing methodologies:

- ☑ Statement coverage
- ☑ branch coverage
- ☑ path coverage
- ☑ condition coverage
- ☑ mutation testing
- ☑ data flow-based testing

Statement Coverage

⌘ Statement coverage methodology:

☑ design test cases so that

☑ every statement in a program is executed at least once.

Statement Coverage

⌘ The principal idea:

☐ unless a statement is executed,

☐ we have no way of knowing if an error exists in that statement.

Statement coverage criterion

⌘ Based on the observation:

☑ an error in a program can not be discovered:

☒ unless the part of the program containing the error is executed.

Statement coverage criterion

⌘ Observing that a statement behaves properly for one input value:

☐ no guarantee that it will behave correctly for all input values.

Example

```
⌘ int f1(int x, int y){  
⌘ 1 while (x != y){  
⌘ 2   if (x > y) then Euclid's GCD Algorithm  
⌘ 3     x = x - y;  
⌘ 4   else y = y - x;  
⌘ 5 }  
⌘ 6 return x; }
```

Euclid's GCD computation algorithm

⌘ By choosing the test set

$\{(x=3, y=3), (x=4, y=3), (x=3, y=4)\}$

☑ all statements are executed at least once.

Branch Coverage

⌘ Test cases are designed such that:

- ☑ different branch conditions
- ☒ given true and false values in turn.

Branch Coverage



- ⌘ Branch testing guarantees statement coverage:
 - ☑ a stronger testing compared to the statement coverage-based testing.

Stronger testing

⌘ Test cases are a superset of a weaker testing:

☑ discovers at least as many errors as a weaker testing

☑ contains at least as many significant test cases as a weaker test.

Example

```
⌘ int f1(int x,int y){  
⌘ 1 while (x != y){  
⌘ 2     if (x>y) then  
⌘ 3         x=x-y;  
⌘ 4     else y=y-x;  
⌘ 5 }  
⌘ 6 return x;     }
```

Example



⌘ Test cases for branch coverage can be:

⌘ $\{(x=3, y=3), (x=3, y=2), (x=4, y=3), (x=3, y=4)\}$

Condition Coverage

⌘ Test cases are designed such that:

☑ each component of a composite conditional expression

☒ given both true and false values.

Example

⌘ Consider the conditional expression

⊡ $((c1.and.c2).or.c3)$:

⌘ Each of $c1$, $c2$, and $c3$ are exercised at least once,

⊡ i.e. given true and false values.

Branch testing

- ⌘ Branch testing is the simplest condition testing strategy:
 - ⊡ compound conditions appearing in different branch statements
 - ⊗ are given true and false values.

Branch testing



⌘ Condition testing

☑ stronger testing than branch testing:

⌘ Branch testing

☑ stronger than statement coverage testing.

Condition coverage

⌘ Consider a boolean expression having n components:

☑ for condition coverage we require 2^n test cases.

Condition coverage



⌘ Condition coverage-based testing technique:

☑ practical only if n (the number of component conditions) is small.

Path Coverage



- ⌘ Design test cases such that:
 - ☑ all linearly independent paths in the program are executed at least once.

Linearly independent paths

⌘ Defined in terms of

☐ control flow graph (CFG) of a program.

Path coverage-based testing

⌘ To understand the path coverage-based testing:

☑ we need to learn how to draw control flow graph of a program.

Control flow graph (CFG)

⌘ A control flow graph (CFG) describes:

☑ the sequence in which different instructions of a program get executed.

☑ the way control flows through the program.

How to draw Control flow graph?

- ⌘ Number all the statements of a program.
- ⌘ Numbered statements:
 - ☑ represent nodes of the control flow graph.

How to draw Control flow graph?

⌘ An edge from one node to another node exists:

⊡ if execution of the statement representing the first node

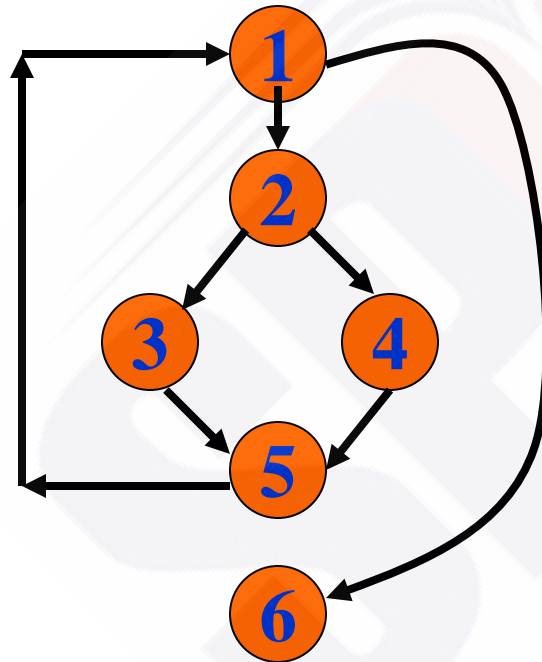
⊗ can result in transfer of control to the other node.

Example



```
⌘ int f1(int x,int y){  
⌘ 1 while (x != y){  
⌘ 2     if (x>y) then  
⌘ 3         x=x-y;  
⌘ 4     else y=y-x;  
⌘ 5 }  
⌘ 6 return x;     }
```

Example Control Flow Graph



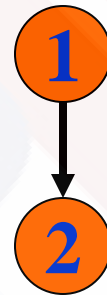
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How to draw Control flow graph?

⌘ Sequence:

⌘ 1 $a=5;$

⌘ 2 $b=a*b-1;$



How to draw Control flow graph?

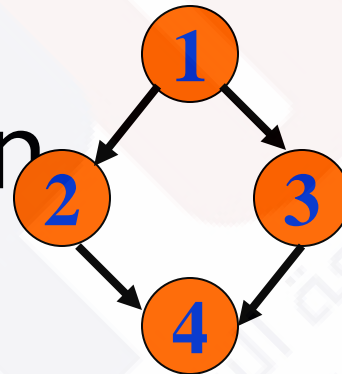
⌘ Selection:

☒ 1 if($a > b$) then

☒ 2 $c = 3;$

☒ 3 else $c = 5;$

☒ 4 $c = c * c;$



How to draw Control flow graph?

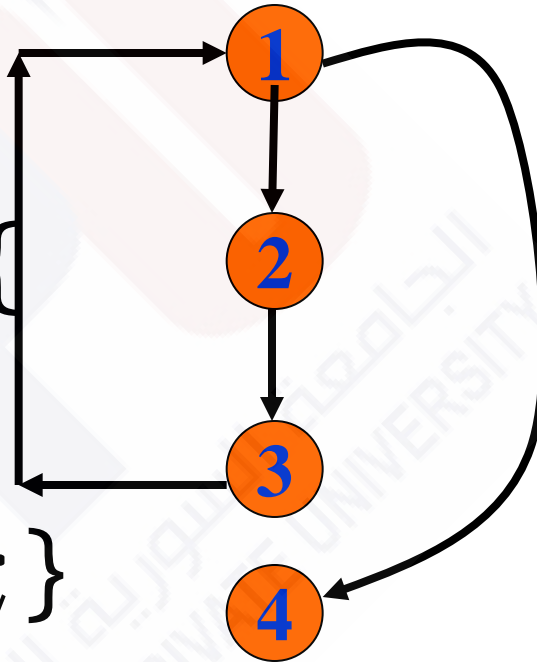
⌘ Iteration:

⌘ 1 while(a > b) {

⌘ 2 b = b * a;

⌘ 3 b = b - 1; }

⌘ 4 c = b + d;



Path



- ⌘ A path through a program:
 - ☑ a node and edge sequence from the starting node to a terminal node of the control flow graph.
 - ☑ There may be several terminal nodes for program.

Independent path



⌘ Any path through the program:

☑ introducing at least one new node:

☒ that is not included in any other independent paths.

Independent path

⌘ It is straight forward:

☑ to identify linearly independent paths of simple programs.

⌘ For complicated programs:

☑ it is not so easy to determine the number of independent paths.

McCabe's cyclomatic metric

⌘ An upper bound:

☒ for the number of linearly independent paths of a program

⌘ Provides a practical way of determining:

☒ the maximum number of linearly independent paths in a program.

McCabe's cyclomatic metric

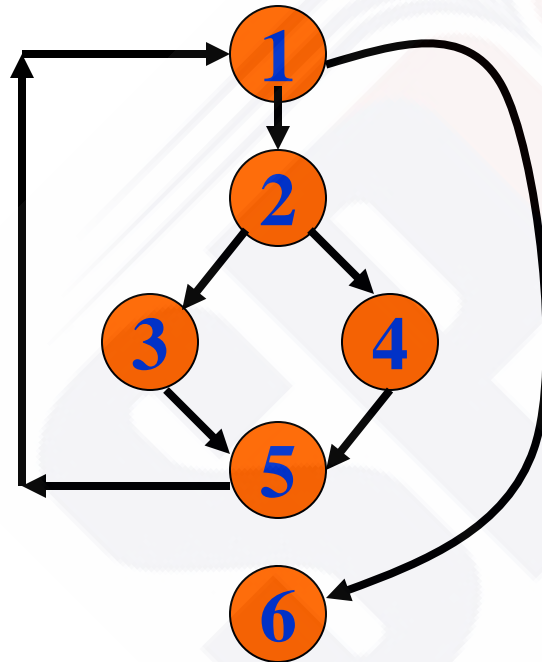
⌘ Given a control flow graph G , cyclomatic complexity $V(G)$:

⊠ $V(G) = E - N + 2$

⊠ N is the number of nodes in G

⊠ E is the number of edges in G

Example Control Flow Graph



Example



⌘ Cyclomatic complexity =
 $7 - 6 + 2 = 3.$

Cyclomatic complexity

⌘ Another way of computing cyclomatic complexity:

☐ inspect control flow graph

☐ determine number of bounded areas in the graph

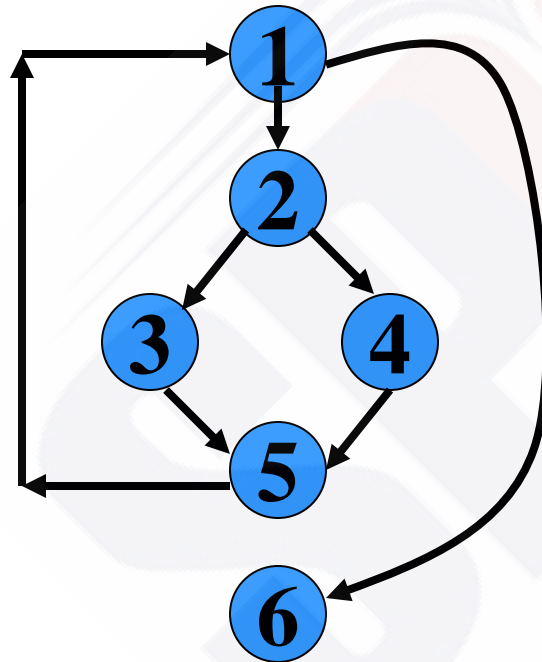
⌘ $V(G) = \text{Total number of bounded areas} + 1$

Bounded area



⌘ Any region enclosed by a nodes and edge sequence.

Example Control Flow Graph



Example

⌘ From a visual examination of the CFG:

☑ the number of bounded areas is 2.

☑ cyclomatic complexity = $2 + 1 = 3$.

Cyclomatic complexity

⌘ McCabe's metric provides:

☒ a quantitative measure of testing difficulty and the ultimate reliability

⌘ Intuitively,

☒ number of bounded areas increases with the number of decision nodes and loops.

Cyclomatic complexity

- ⌘ The first method of computing $V(G)$ is amenable to automation:
 - ☑ you can write a program which determines the number of nodes and edges of a graph
 - ☑ applies the formula to find $V(G)$.

Cyclomatic complexity

⌘ The cyclomatic complexity of a program provides:

- ☑ a lower bound on the number of test cases to be designed
- ☑ to guarantee coverage of all linearly independent paths.

Cyclomatic complexity

- ⌘ Defines the number of independent paths in a program.
- ⌘ Provides a lower bound:
 - ⏏ for the number of test cases for path coverage.

Cyclomatic complexity

- ⌘ Knowing the number of test cases required:
 - ☒ does not make it any easier to derive the test cases,
 - ☒ only gives an indication of the minimum number of test cases required.

Path testing



⌘ The tester proposes:

☑ an initial set of test data using his experience and judgement.

Path testing

- ⌘ A dynamic program analyzer is used:
 - ☑ to indicate which parts of the program have been tested
 - ☑ the output of the dynamic analysis
 - ☒ used to guide the tester in selecting additional test cases.

Derivation of Test Cases

- ⌘ Let us discuss the steps:
 - ☑ to derive path coverage-based test cases of a program.

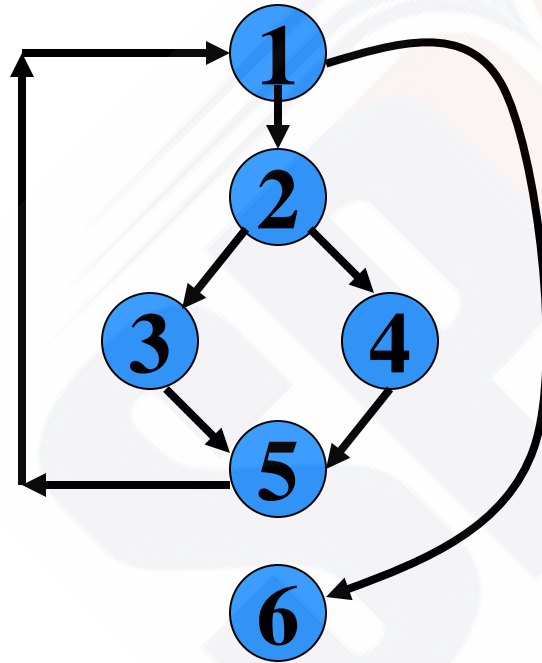
Derivation of Test Cases

- ⌘ Draw control flow graph.
- ⌘ Determine $V(G)$.
- ⌘ Determine the set of linearly independent paths.
- ⌘ Prepare test cases:
 - ☑ to force execution along each path.

Example

```
⌘ int f1(int x,int y){  
⌘ 1 while (x != y){  
⌘ 2     if (x>y) then  
⌘ 3         x=x-y;  
⌘ 4     else y=y-x;  
⌘ 5 }  
⌘ 6 return x;     }
```

Example Control Flow Diagram



Derivation of Test Cases

⌘ Number of independent paths: 3

☒ 1,6 test case ($x=1, y=1$)

☒ 1,2,3,5,1,6 test case ($x=1, y=2$)

☒ 1,2,4,5,1,6 test case ($x=2, y=1$)

An interesting application of cyclomatic complexity

⌘ Relationship exists between:

☑ McCabe's metric

☑ the number of errors existing in the code,

☑ the time required to find and correct the errors.

Cyclomatic complexity

⌘ Cyclomatic complexity of a program:

☒ also indicates the psychological complexity of a program.

☒ difficulty level of understanding the program.

Cyclomatic complexity

- ⌘ From maintenance perspective,
 - ☑ limit cyclomatic complexity
 - ☒ of modules to some reasonable value.
 - ☑ Good software development organizations:
 - ☒ restrict cyclomatic complexity of functions to a maximum of ten or so.

Summary



⌘ White box testing:

- ☑ requires knowledge about internals of the software.

- ☑ Design and code is required.

Summary



⌘ We have discussed a few white-box test strategies.

☑ Statement coverage

☑ branch coverage

☑ condition coverage

☑ path coverage

Summary



⌘ A stronger testing strategy:

☑ provides more number of significant test cases than a weaker one.

☑ Condition coverage is strongest among strategies we discussed.

Summary



- ⌘ We discussed McCabe's Cyclomatic complexity metric:
 - ☑ provides an upper bound for linearly independent paths
 - ☑ correlates with understanding, testing, and debugging difficulty of a program.